

MEA 2013-2014

Teacher: Claudia Valle

Start Date:

| Course: Geo  | metry B |
|--------------|---------|
| Student:     |         |
| Completed Da | ite:    |

## **Unit 6: Transformational Geometry**

**Objectives:** Students will understand how execute various types of transformations. Students will understand how to identify and describe different types of transformations. Students will understand how to represent magnitude and direction with a vector and use them to solve real life problems.

**Essential Questions:** What is a transformation, and what are the 3 basic types of transformations? How can vectors be used to describe translations? How can a figure be transformed multiple times?

TEKS Standards: G.2.A, G.2.B, G.5.C, G.7.A, G.10.A, G.11.A, G.11.B, G.11.D

Geometry

- (2) Geometric structure. The student analyzes geometric relationships in order to make and verify conjectures. The student is expected to:
- (A) use constructions to explore attributes of geometric figures and to make conjectures about geometric relationships; and
- (B) make conjectures about angles, lines, polygons, circles, and three-dimensional figures and determine the validity of the conjectures, choosing from a variety of approaches such as coordinate, transformational, or axiomatic.
- (5) Geometric patterns. The student uses a variety of representations to describe geometric relationships and solve problems. The student is expected to:
- (C) use properties of transformations and their compositions to make connections between mathematics and the real world, such as tessellations; and

- (7) Dimensionality and the geometry of location. The student understands that coordinate systems provide convenient and efficient ways of representing geometric figures and uses them accordingly. The student is expected to:
- (A) use one- and two-dimensional coordinate systems to represent points, lines, rays, line segments, and figures;
- (10) Congruence and the geometry of size. The student applies the concept of congruence to justify properties of figures and solve problems. The student is expected to:
- (A) use congruence transformations to make conjectures and justify properties of geometric figures including figures represented on a coordinate plane; and
- (11) Similarity and the geometry of shape. The student applies the concepts of similarity to justify properties of figures and solve problems. The student is expected to:
- (A) use and extend similarity properties and transformations to explore and justify conjectures about geometric figures;
- (B) use ratios to solve problems involving similar figures;
- (D) describe the effect on perimeter, area, and volume when one or more dimensions of a figure are changed and apply this idea in solving problems.

#### Turn In:

| Assignment # | Activity                        | TEKS   |
|--------------|---------------------------------|--|
| 39           | Reflections                     | G.2.A, G.2.B, G.7.A, G.10.A                                      |
| 40           | Translations                    | G.2.A, G.2.B, G.7.A, G.10.A                                      |
| 41           | Rotations                       | G.2.A, G.2.B, G.7.A, G.10.A                                      |
| 42           | Compositions of Transformations | G.5.C, G.10.A  |
| 43           | Symmetry                        | G.2.B, G.5.C, G.10.A   |
| 44           | Tessellations                   | G.5.C  |
| 45           | Dilations                       | G.2.A, 11.A, G.11.B, G.11.D                                      |
| 46           | Unit 6 Test                     | G.2.A, G.2.B, G.5.C, G.7.A,<br>G.10.A, G.11.A, G.11.B,<br>G.11.D |

## Reteach

### Reflections

An isometry is a transformation that does not change the shape or size of a figure. Reflections, translations, and rotations are all isometries.

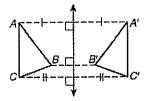
A reflection is a transformation that flips a figure across a line.

Reflection Not a Reflection





The line of reflection is the perpendicular bisector of each segment joining each point and its image.



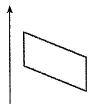
Tell whether each transformation appears to be a reflection.

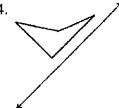
1.





Copy each figure and the line of reflection. Draw the reflection of the figure across the line.





# 12-1

# **LESSON** Reteach

### Reflections continued

| Across the x-axis                         | Across the <i>y</i> -axis | Across the line $y = x$     |
|---|---------------------------|-----------------------------|
| ∱ <i>y</i><br>• <i>FI</i> ( <i>x, y</i> ) | R'(-x, y)•<- ◆R(x, y)     | P'(y, x)                    |
| R'(x, -y)                                 | 0                         | $(x, y) \rightarrow (y, x)$ |

Reflect  $\triangle FGH$  with vertices F(-1, 4), G(2, 4), and H(4, 1)across the x-axis.

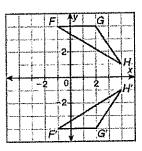
The reflection of (x, y) is (x, -y).

$$F(-1, 4) \rightarrow F'(-1, -4)$$

$$G(2, 4) \rightarrow G'(2, -4)$$

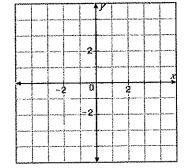
$$H(4, 1) \rightarrow H'(4, -1)$$

Graph the preimage and image.

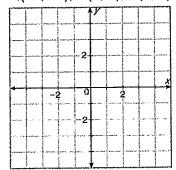


Reflect the figure with the given vertices across the line.

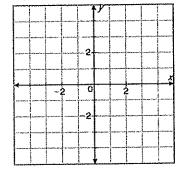
5. M(2, 4), N(4, 2), P(3, -2); y-axis



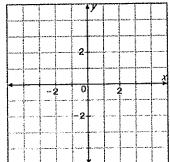
7. Q(-3, -1), R(2, 4), S(2, 1); x-axis



6. T(-4, 1), U(-3, 4), V(2, 3), W(0, 1); x-axis



8. A(-2, 4), B(1, 1), C(-5, -1); y = x



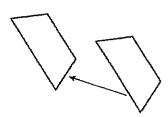
### Reteach

# 12-2

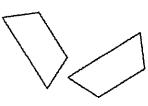
### Translations

A translation is a transformation in which all the points of a figure are moved the same distance in the same direction.

**Translation** 

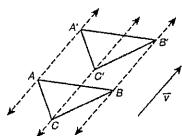


Not a Translation



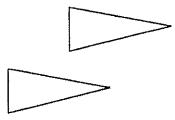
A translation is a transformation along a vector such that each segment joining a point and its image has the same length as the vector and is parallel to the vector.

 $\overline{AA'}, \overline{BB'}$ , and  $\overline{CC'}$  have the same length as  $\overline{v}$  and are parallel to  $\overline{v}$ .

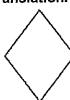


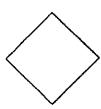
Tell whether each transformation appears to be a translation.

1



2.





Copy each figure and the translation vector. Draw the translation of the figure along the given vector.

3.





### Reteach

## 12-2

### Translations continued

| Translations in the Coordinate Plane                                    |   |   |
|---|---|---|
| Horizontal Translation<br>Along Vector ⟨a, 0⟩                           | Horizontal Translation<br>Along Vector (0, <i>b</i> ) | Horizontal Translation<br>Along Vector ⟨a, b⟩                   |
| $(x, y) \xrightarrow{\Gamma(x + a, y)}$ $(x, y) \rightarrow (x + a, y)$ | $(x, y) \rightarrow (x, y + b)$                       | $T(x + a, y + b)$ $T(x, y)$ $(x, y) \rightarrow (x + a, y + b)$ |

Translate  $\triangle JKL$  with vertices J(0, 1), K(4, 2), and L(3, -1) along the vector  $\langle -4, 2 \rangle$ .

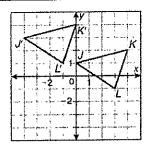
The image of (x, y) is (x - 4, y + 2).

$$J(0, 1) \rightarrow J'(0-4, 1+2) = J'(-4, 3)$$

$$K(4, 2) \rightarrow K'(4-4, 2+2) = K'(0, 4)$$

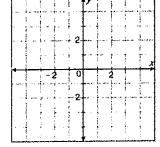
$$L(3, -1) \rightarrow L'(3 - 4, -1 + 2) = L'(-1, 1)$$

Graph the preimage and image.

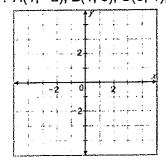


# Translate the figure with the given vertices along the given vector.

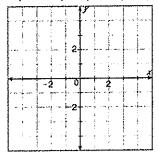
5. E(-2, -4), F(3, 0), G(3, -4); (0, 3)



7. A(1, -2), B(1, 0), C(3, 1), D(4, -3); \( -5, 3 \)



6. P(-4, -1), Q(-1, 3), R(0, -4); (4, 1)



8. *G*(-3, 4), *H*(4, 3), *J*(1, 2); ⟨-1, -6⟩

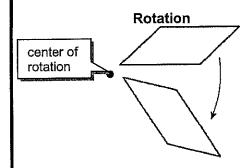


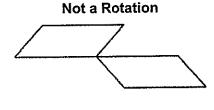
# Reteach

# 12-3

### Rotations

A rotation is a transformation that turns a figure around a fixed point, called the center of rotation.



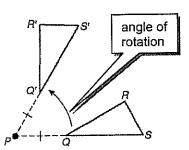


A rotation is a transformation about a point P such that each point and its image are the same distance from P.

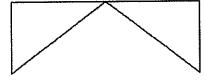
$$PQ = PQ'$$

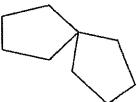
$$PR = PR'$$

$$PS = PS'$$



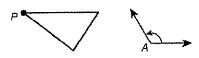
Tell whether each transformation appears to be a rotation.

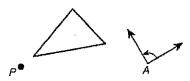




Copy each figure and the angle of rotation. Draw the rotation of the figure about point P by m $\angle A$ .

3.





# Reteach

### Rotations continued

| Rotations in the Coordinate Plane   |   |  |
|---|---|--|
| By 90° About the Origin   | By 180° About the Origin  |  |
| $N'(-y, x) \xrightarrow{90^{\circ}} N(x, y)$ $(x, y) \rightarrow (-y, x)$ | $ \begin{array}{c} \uparrow y \\ \uparrow N(x, y) \\ \downarrow 0 $ |  |

Rotate  $\triangle MNP$  with vertices M(1, 1), N(2, 4), and P(4, 3) by 180° about the origin.

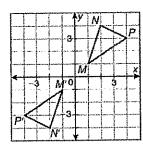
The image of (x, y) is (-x, -y).

$$M(1, 1) \rightarrow M'(-1, -1)$$

$$N(2, 4) \rightarrow N'(-2, -4)$$

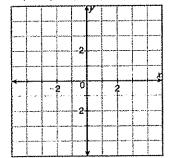
$$P(4, 3) \rightarrow P'(-4, -3)$$

Graph the preimage and image.

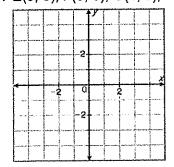


### Rotate the figure with the given vertices about the origin using the given angle.

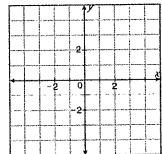
5. R(0, 0), S(3, 1), T(2, 4); 90°



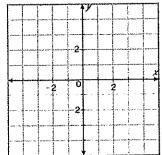
7. E(0, 3), F(3, 5), G(4, 0); 180°



6. A(0, 0), B(-4, 2), C(-1, 4); 180°



8.  $U(1, -1), V(4, -2), W(3, -4); 90^{\circ}$ 

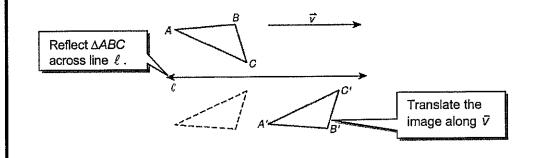


### Reteach

### **Compositions of Transformations**

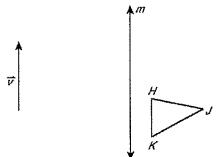
A **composition of transformations** is one transformation followed by another. A **glide reflection** is the composition of a translation and a reflection across a line parallel to the vector of the translation.

Reflect  $\triangle ABC$  across line  $\ell$  along  $\vec{v}$  and then translate it parallel to  $\vec{v}$ .

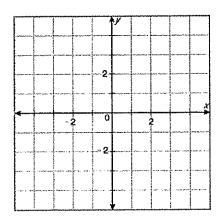


### Draw the result of each composition of transformations.

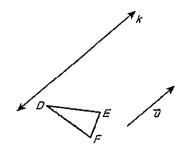
1. Translate  $\triangle HJK$  along  $\vec{v}$  and then reflect it across line m.



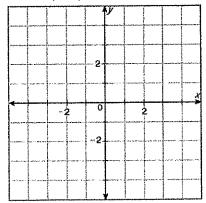
3.  $\triangle ABC$  has vertices A(0, -1), B(3, 4), and C(3, 1). Rotate  $\triangle ABC$  180° about the origin and then reflect it across the *x*-axis.



2. Reflect  $\triangle DEF$  across line k and then translate it along  $\bar{u}$ .



4.  $\triangle QRS$  has vertices Q(2, 1), R(4, -2), and S(1, -3). Reflect  $\triangle QRS$  across the *y*-axis and then translate it along the vector  $\langle 1, 3 \rangle$ .



# 12-4

# LESSON Reteach

# Compositions of Transformations continued

Any translation or rotation is equivalent to a composition of two reflections.

### **Composition of Two Reflections**

To draw two parallel lines of reflection that produce a translation:

- Draw  $\overline{PP'}$ , a segment connecting a preimage point P and its corresponding image point P'. Draw the midpoint M of  $\overline{PP'}$ .
- Draw the perpendicular bisectors of  $\overline{PM}$  and  $\overline{P'M}$ .

To draw two intersecting lines that produce a rotation with center C:

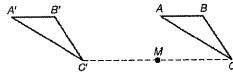
- Draw  $\angle PCP'$ , where P is a preimage point and P' is its corresponding image point. Draw  $\overline{CX}$ , the angle bisector of  $\angle PCP'$ .
- Draw the angle bisectors of ∠PCX and ∠P'CX.

Copy  $\triangle ABC$  and draw two lines of reflection that produce the translation  $\triangle ABC \rightarrow \triangle A'B'C'$ .

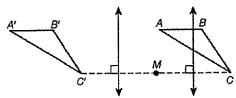




**Step 1** Draw  $\overline{CC'}$  and the midpoint M of  $\overline{CC'}$ .



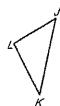
**Step 2** Draw the perpendicular bisectors of  $\overline{CM}$  and  $\overline{C'M}$ .

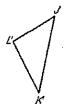


Copy each figure and draw two lines of reflection that produce an equivalent transformation.

5. translation:

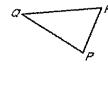
$$\triangle JKL \rightarrow \triangle J'K'L'$$

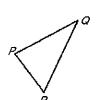




6. rotation with center C:

$$\triangle PQR \rightarrow \triangle P'Q'R'$$





| Name Date Class | Name |  | Class |
|-----------------|------|--|-------|
|-----------------|------|--|-------|



# Reteach

# Symmetry

A figure has **symmetry** if there is a transformation of the figure such that the image and preimage are identical. There are two kinds of symmetry.

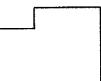
| preimage are identical. There are two kinds of symmetry. |   |   |   |
|--|---|---|---|
| Line Symmetry  | The figure has a <b>line of</b> congruent halves.  one line of symmetry   | symmetry that divides the   | e figure into two no line symmetry            |
| Rotational<br>Symmetry                                   | <ul> <li>coincides with the origin</li> <li>The smallest angle thr         with itself is called the</li> <li>The number of times to</li> </ul> | I between 0° and 360°, the hal.  rough which the figure is rougle of rotational symmethat you can get an identic of rotation is called the order of 120°  3 | otated to coincide<br>etry.<br>al figure when |

Tell whether each figure has line symmetry. If so, draw all lines of symmetry.

1.



2.



Tell whether each figure has rotational symmetry. If so, give the angle of rotational symmetry and the order of the symmetry.

3





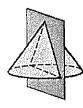
### Reteach

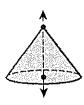
## Symmetry continued

Three-dimensional figures can also have symmetry.

| Symmetry in Three Dimensions | Description   | Example |
|------------------------------|---|---------|
| Plane Symmetry               | A plane can divide a figure into two congruent halves.  |         |
| Symmetry About an Axis       | There is a line about which a figure can be rotated so that the image and preimage are identical. |         |

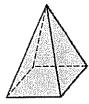
A cone has both plane symmetry and symmetry about an axis.



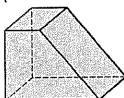


Tell whether each figure has plane symmetry, symmetry about an axis, both, or neither.

5. square pyramid



6. prism



7. triangular pyramid



8. cylinder

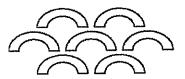


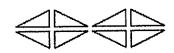
## Reteach

12-6

### Tessellations

A pattern has **translation symmetry** if it can be translated along a vector so that the image coincides with the preimage. A pattern with **glide reflection symmetry** coincides with its image after a glide reflection.



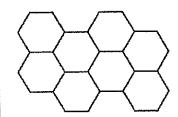


**Translation Symmetry** 

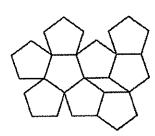
Translation Symmetry and Glide Reflection Symmetry

A **tessellation** is a repeating pattern that completely covers a plane with no gaps or overlaps.

Tessellation

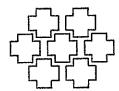


Not a Tessellation

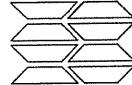


Identify the symmetry in each pattern.

1.



2.



Copy the given figure and use it to create a tessellation.

3.



| Name   | Date | Class |
|--------|------|-------|
| 101110 |      |       |



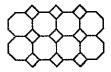
### Reteach

# 12-6

### Tessellations continued

A regular tessellation is formed by congruent regular polygons. A semiregular tessellation is formed by two or more different regular polygons.





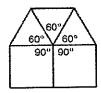
### **Regular Tessellation**

Semiregular Tessellation

In a tessellation, the measures of the angles that meet at each vertex must have a sum of 360°.





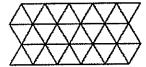


$$90^{\circ} + 90^{\circ} + 90^{\circ} + 90^{\circ} = 360^{\circ}$$

$$120^{\circ} + 120^{\circ} + 120^{\circ} = 360^{\circ}$$

$$3(60^\circ) + 2(90^\circ) = 360^\circ$$

Classify each tessellation as regular, semiregular, or neither.



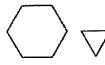


Determine whether the given regular polygon(s) can be used to form a tessellation. If so, draw the tessellation.

7.







## Reteach

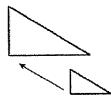
# 12-7

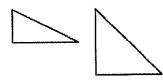
### Dilations

A dilation is a transformation that changes the size of a figure but not the shape.

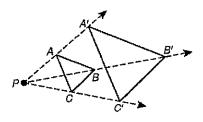
Dilation



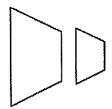


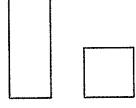


A dilation is a transformation in which the lines connecting every point A with its image A' all intersect at point P, called the **center of dilation**.



Tell whether each transformation appears to be a dilation.





Copy teach triangle and center of dilation. Draw the image of the triangle under a dilation with the given scale factor.

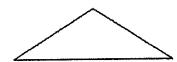
3. scale factor: 2





4. scale factor:





# Reteach

### Dilations continued

| Dilations in the Coordinate Plane |                               |  |
|-----------------------------------|-------------------------------|--|
| For <i>k</i> > 1                  | For 0 < k < 1                 |  |
| $(x, y) \to (kx, ky)$             | $(x, y) \rightarrow (kx, ky)$ |  |

If k has a negative value, the preimage is rotated by 180°.

Draw the image of  $\triangle EFG$  with vertices E(0, 0), F(0, 1), and G(2, 1) under a dilation with a scale factor of -3 and centered at the origin.

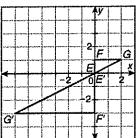
The image of (x, y) is (-3x, -3y).

$$E(0, 0) \rightarrow E'(0(-3), 0(-3)) \rightarrow E'(0, 0)$$

$$F(0, 1) \rightarrow F'(0(-3), 1(-3)) \rightarrow F'(0, -3)$$

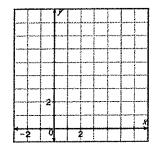
$$G(2, 1) \rightarrow G'(2(-3), 1(-3)) \rightarrow G'(-6, -3)$$

Graph the preimage and image.

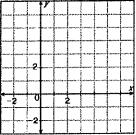


Draw the image of the figure with the given vertices under a dilation with the given scale factor and centered at the origin.

5. J(0, 0), K(-1, 2), L(3, 4); scale factor: 2



6. A(0, 0), B(0, 6), C(6, 3); scale factor:  $\frac{1}{3}$ 



7. R(1, 0), S(1, -2), T(-1, -2);

